

Design of Artificial Neural Networks based on Genetic Algorithms to Forecast Time Series

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Abstract— In this work an initial approach to design Artificial Neural Networks (ANN) using Genetic Algorithms (GA) is tackle. A key issue for these kind of approaches is what information contains, or is included, in the chromosome that represent an ANN, and there are two principal ideas about these question: first, information about parameters of the topology, architecture, learning parameters, etc. of ANN, i.e. Direct Encoding; second, initial information related to a constructive method that give rise to an ANN topology or architecture, i.e Indirect Encoding. The results for an Direct Encoding (in order to compare with Indirect Encoding developed in future works), for design ANN to NN3 Forecasting Time Series Competition.

I. INTRODUCTION

THIS document report the methodology to carry out the automatic design of ANN that tackle the Forecasting Time Series problem taken from NN3 Forecasting Time Series Competition [1].

According to [2], that show the approximation capability of Multilayer Perceptron (MLP), we have focused on MLP with only one hidden layer, and Backpropagation (BP) to forecasting time series.

Several works approach the design of ANN using Evolutionary Techniques. Some of them uses Direct Encoding Scheme [3,4], the others using Indirect Encoding Scheme [5,6,7]. Ajith Abraham [8] shows an automatic framework for optimization ANN in an adaptive way. And [9] try to spell out the future trends of the field.

II. FORECASTING TIME SERIES WITH ANN

In order to make that a single ANN could work, and forecasting, with time series values, an initial step from original values of time series have to be done, i.e. normalize the data. And, once the ANN gives those values, the inverse process is done. This step is important as the ANN will learn just the normalized values.

The problem of forecasting time series with ANN is

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considered as obtain the relationship of the value of period “ t ” (i.e. the net has only one output neuron) and the values of previous periods, i.e the function:

$$a_t = f(a_{t-1}, a_{t-2}, \dots, a_{t-k})$$

Therefore, the time series will be transform into a pattern set, it depend on the k inputs nodes of a particular ANN. Each pattern consists in:

- “ k ” inputs values, that correspond to “ k ” normalized previous values of period t : $a_{t-1}, a_{t-2}, \dots, a_{t-k}$
- One output value, that corresponds to normalized time series value of period t .

The complete patterns set are ordered into the same way the time series is. This patterns set will be used to train and test the ANN, then it will be split into two sets, train and test sets. The train set will be obtained from the first $m\%$ (e.g $m=70$) and the test set will be obtained from the rest of the complete patterns set.

If hand design of ANN is carry out, several topologies (i.e. different number of inputs nodes and number of different number of neurons of only one hidden layer), with different learning rates are trained. For each of them, train and test error are obtained, and one with better generalization capability (i.e. less test error and a good train error) is selected to generate forecast values.

III. ANN DESIGN WITH GENETIC ALGORITHMS

The problem of design ANN could be seen as a search problem into the space of all possible ANN. And that search can be done by a GA [10] using exploitation and exploration.

There three crucial issues: the solution’s space; how each solutions is codified into a chromosome, i.e. encoding scheme; and what is looking for, translated into the function fitness.

The final object of our approach is consider Sparsely Connected MLP to forecast time series, and use both Indirect Encoding Scheme, one based on Cellular Automata [11] and other based on Bidimensional Grammar [12], to design ANN using GA.

But as a first approach to design ANN to forecasting time series, a Direct Encoding Scheme for Full Connected MLP has been considered. For this Direct Encoding Scheme the information placed into the chromosome is:

- Number of inputs nodes (i).

- Number of hidden nodes (h).
- Learning rate, for BP learning algorithm (α).

The value of learning rate, “ α ”, is between 0 and 1, and the value of “ i ” and “ h ” is limited by a maximum number of inputs nodes (\max_inputs) and a maximum number of hidden nodes (\max_hidden), respectively. These maximum values are related, by a factor “ a ”, with the number of periods of time series what values are known (nts), see (1)

$$\begin{aligned}\max_inputs &= a \times nts; \\ \max_hidden &= 2 \times \max_inputs; (1) \\ a &= 0.3\end{aligned}$$

Into the chromosome, two decimal digits, i.e two genes, are used to codified the value “ i ”, other two for “ h ” and the last two for “ α ”. This way, the values of “ i ”, “ h ” and “ α ” are obtained, from the chromosome, as it can see in (2)

$$\begin{aligned}chrom : & gi_1 gi_2 gh_1 gh_2 g\alpha_1 g\alpha_2 \\ i &= \max_inputs \times \frac{(gi_1 \cdot 10 + gi_2)}{100}; \\ h &= \max_hiddens \times \frac{(gh_1 \cdot 10 + gh_2)}{100}; (2) \\ \alpha &= \frac{(g\alpha_1 \cdot 10 + g\alpha_2)}{100}\end{aligned}$$

The search process that GA is, begins with a random population, i.e set of randomly generated chromosomes. Later, the fitness value for each one of the individual of the population is obtained (a). Once that it is already done the GA operators as Elitism, Selection, Crossover and Mutation are applied in order to generate the population of next generation, i.e. set of chromosomes (b). The steps (a) and (b) are iteratively executed till a maximum number of generations is reached.

To obtained the fitness value of a chromosome:

1. The train patterns and test patterns sets are obtained, depending on the number of inputs nodes of the net, as was said above (sec.II).
2. Then, the connection weights are randomly initialized, and the net is trained (using Stuttgart Neural Network Simulator (SNNS) binary tools [13]) a maximum training cycles.

The fitness value will be the minimum error test reached in training process, it doesn't have to be in the last training cycle. The architecture of the net (topology + connections weights) when the test error is minimum in training process is saved to be used later for forecasting time series values.

Once that GA reaches the last generation, the best

individual from all generations is used to forecast the time series.

IV. CONCLUSION

The final object of our approach is consider Sparsely Connected MLP to forecast time series, and use both Indirect Encoding Scheme, one based on Cellular Automata [11] and other based on Bidimensional Grammar [12], to design ANN using GA.

APPENDIX

Stuttgart Neural Network Simulator (SNNS) binary tools [13], `ff_bignet` and `batchman`, has been used for generate and training ANN.

The whole source code is available in {`ggutierr.jperalta`}@inf.uc3m.es.

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